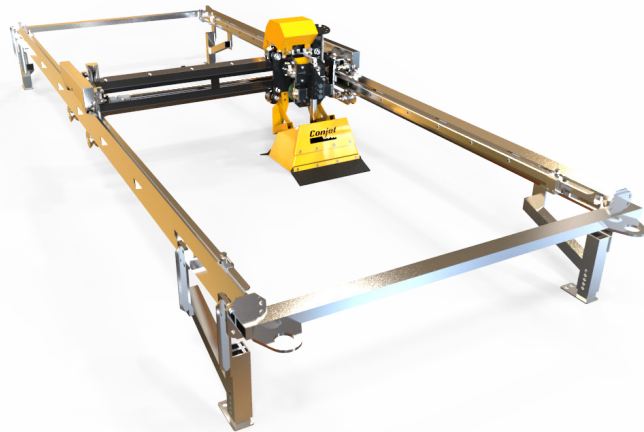


# JETFRAME 137/157

*Remove concrete  
anywhere*



Conjet's Jetframe 137/157 hydrodemolition system allows selective removal of concrete in areas inaccessible to standard hydro-demolition robots or other concrete removal technologies. The Jetframe is remotely operated from up to 100 meters using the computer control unit (CCU) or any 7-series Conjet robot. Jetframe 137/157 consists of a rectangular frame supported on four legs that utilizes the feed beam and cradle from a Robot 327 or 557 or it can be purchased as a complete assembly.

It can be bolted to the concrete surface being repaired or mounted on a tool carrier, such as a fourwheel drive forklift truck, skylift platform or supported from winches.

The Jetframe 137/157 is specifically designed to remove concrete in the most difficult-to-reach places. It can also be quickly dismantled into components small and light enough to be carried by one man. It can operate on a variety of horizontal, vertical and angled surfaces, including ceilings and underneath bridge decks.

Optimal for:

- Bridge pillars
- Dam surfaces and spillways
- Dry docks and quay decks



## TECHNICAL DATA – STANDARD CONFIGURATION

Length (can be adjusted)	4 000 mm (13ft 2in)
Weight	1 500 mm (4ft 11in) / 2 000 mm (6ft 7in)
Cutting width	2 140 mm (7ft)
Cutting length	3 500 mm (11ft 6in)
Height	800 mm (4ft 7in)
Weight	650 kg (1 430lb)
Maximum reaction force	2 000 N
Powered and controlled by	Conjet CCU 217 or 7-Series Robot

**CE, EMC certified**

## FEATURES

- Handles the most inaccessible areas
- Operates under water
- Remotly controlled via CCU or any 7-Series Robot
- Can operate at long distance from the control unit
- Rigid framework to maximize keeping the precision high
- Can be dismantled for transportation and easier handling
- Customizable on request for special projects

## TOOLS



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